# Online Aggregation and Second Order Algorithms

Mathematical Analysis of Machine Learning Algorithms (Chapter 15)

# Log-Loss for Density Estimation

Consider conditional density estimation with log-loss (negative-log-likelihood), where the loss function is

$$\phi(\boldsymbol{w},\boldsymbol{Z})=-\ln p(\boldsymbol{Y}|\boldsymbol{w},\boldsymbol{X}).$$

### Example 1

For discrete  $y \in \{1, \ldots, K\}$ , we have

$$p(y|w,x) = \frac{\exp(f_y(w,x))}{\sum_{k=1}^K \exp(f_k(w,x))},$$

and (let Z = (x, y)):

$$\phi(w,Z) = -f_y(w,x) + \ln \sum_{k=1}^{K} \exp(f_k(w,x)).$$

### Example 2 (More Log-Loss Example)

For least squares regression with noise variance  $\sigma^2$ , we may have

$$p(y|w,x) = \frac{1}{\sqrt{2\pi\sigma}} \exp\left(-\frac{(y-f(w,x))^2}{2\sigma^2}\right),$$

and (let Z = (x, y)):

$$\phi(\boldsymbol{w},\boldsymbol{Z}) = \frac{(\boldsymbol{y} - f(\boldsymbol{w},\boldsymbol{x}))^2}{2\sigma^2} + \ln(\sqrt{2\pi}\sigma).$$

We may also consider the noise as part of the model parameter, and let

$$p(y|[w,\sigma],x) = \frac{1}{\sqrt{2\pi\sigma}} \exp\left(-\frac{(y-f(w,x))^2}{2\sigma^2}\right)$$
$$\phi([w,\sigma],Z) = \frac{(y-f(w,x))^2}{2\sigma^2} + \ln(\sqrt{2\pi\sigma}).$$

# **Bayesian Posterior Averaging**

### **Bayesian Posterior Distribution**

Consider a prior  $p_0(w)$  on  $\Omega$ . Given the training data  $S_n = \{Z_1, \ldots, Z_n\}$ , the posterior distribution is

$$p(w|S_n) = \frac{\prod_{i=1}^n p(Y_i|w, X_i) p_0(w)}{\int_{\Omega} \prod_{i=1}^n p(Y_i|w', X_i) p_0(w') \, dw'}.$$
 (1)

The *Bayesian posterior average estimator* is the averaged probability estimate over the posterior

$$\hat{p}(y|x,\mathcal{S}_n) = \int_{\Omega} p(y|w,x) p(w|\mathcal{S}_n) \, dw.$$
(2)

However, we do not assume that the Bayesian assumption holds true in the theoretical analysis.

# Regret Bound: Property of Log-Partition Function

Proposition 3 (Prop 7.16)

Given any function U(w), we have

 $\min_{\boldsymbol{\rho}\in\Delta(\Omega)}\left[\mathbb{E}_{\boldsymbol{W}\sim\boldsymbol{\rho}}\boldsymbol{U}(\boldsymbol{w})+\mathrm{KL}(\boldsymbol{\rho}||\boldsymbol{\rho}_{0})\right]=-\ln\mathbb{E}_{\boldsymbol{W}\sim\boldsymbol{\rho}_{0}}\exp(-\boldsymbol{U}(\boldsymbol{w})),$ 

and the solution is achieved by the Gibbs distribution

 $q(w) \propto p_0(w) \exp(-U(w)).$ 

Here  $\Delta(\Omega)$  denotes the set of probability distributions on  $\Omega$ .

# Regret Bound: Conditional Density Estimation

#### Theorem 4 (Thm 15.3)

We have

$$-\sum_{t=1}^{T} \ln \hat{p}(Y_t, | X_t, \mathcal{S}_{t-1}) = -\ln \mathbb{E}_{w \sim p_0} \prod_{t=1}^{T} p(Y_t | w, X_t)$$
$$= \inf_{q \in \Delta(\Omega)} \left[ -\mathbb{E}_{w \sim q} \sum_{t=1}^{T} \ln p(Y_t | w, X_t) + \mathbb{E}_{w \sim q} \ln \frac{q(w)}{p_0(w)} \right],$$

where  $\Delta(\Omega)$  is the set of probability distributions over  $\Omega$ .

## Proof of Theorem 4

We have

$$\ln \hat{p}(Y_{t}, |X_{t}, S_{t-1}) = \ln \int_{\Omega} p(Y_{t}|w, X_{t}) p(w|S_{t-1}) dw$$
  
=  $\ln \frac{\int_{\Omega} \prod_{i=1}^{t} p(Y_{i}|w, X_{i}) p_{0}(w) dw}{\int_{\Omega} \prod_{i=1}^{t-1} p(Y_{i}|w', X_{i}) p_{0}(w') dw'}$   
=  $\ln \mathbb{E}_{w \in p_{0}} \prod_{i=1}^{t} p(Y_{i}|w, X_{i}) - \ln \mathbb{E}_{w \in p_{0}} \prod_{i=1}^{t-1} p(Y_{i}|w, X_{i}).$ 

By summing over t = 1 to t = T, we obtain

$$\sum_{t=1}^{T} \ln \hat{p}(Y_t, | x_t, \mathcal{S}_{t-1}) = \ln \mathbb{E}_{w \in p_0} \prod_{t=1}^{T} p(Y_t | w, X_t)$$
$$= \sup_{q} \left[ \mathbb{E}_{w \sim q} \ln \prod_{t=1}^{T} p(Y_t | w, X_t) - \mathbb{E}_{w \sim q} \ln \frac{q(w)}{p_0(w)} \right],$$

where the second equality used Proposition 3.

# **Discrete Family of Probability Distributions**

### Corollary 5 (Cor 15.4)

If  $\Omega = \{\textbf{w}_1, \ldots\}$  is discrete, then

$$-\sum_{t=1}^T \ln \hat{p}(Y_t, | X_t, \mathcal{S}_{t-1}) \leq \inf_{w \in \Omega} \left[ -\sum_{t=1}^T \ln p(Y_t | w, X_t) - \ln p_0(w) \right].$$

### Proof.

Given any  $w' \in \Omega$ , if we choose q(w) = 1 when w = w', and q(w) = 0 when  $w \neq w'$ , then from Theorem 4:

$$-\mathbb{E}_{w \sim q} \sum_{t=1}^{T} \ln p(Y_t | w, X_t) + \mathbb{E}_{w \sim q} \ln \frac{q(w)}{p_0(w)} = -\sum_{t=1}^{T} \ln p(Y_t | w', X_t) - \ln p_0(w').$$

# Example: Finite $|\Omega| = N$

Let  $p_0(w) = 1/N$  be the uniform distribution on  $\Omega$ , then we have

$$-\sum_{t=1}^{T}\ln\hat{p}(Y_t,|X_t,\mathcal{S}_{t-1})\leq \inf_{w\in\Omega}\left[-\sum_{t=1}^{T}\ln p(Y_t|w,X_t)+\ln N\right].$$

This means that we have a constant regret which is independent of T. Using online to batch conversion:

$$-\frac{1}{T}\mathbb{E}_{\mathcal{S}_{T}}\sum_{t=1}^{T}\mathbb{E}_{Z\sim\mathcal{D}}\ln\hat{p}(Y|X,\mathcal{S}_{t-1})\leq\inf_{w\in\Omega}\left[-\mathbb{E}_{Z\sim\mathcal{D}}\ln p(Y|w,X)+\frac{\ln N}{T}\right]$$

# **Ridge Regression**

The general regret bound for Bayesian model averaging can be used to analyze the ridge regression method. Consider the following linear prediction problem with least squares loss:

$$f(\boldsymbol{w},\boldsymbol{x}) = \boldsymbol{w}^{\top}\psi(\boldsymbol{x}),$$

with loss function

 $(y-f(w,x))^2.$ 

Consider the following ridge regression estimator:

$$\hat{w}(S_n) = \arg\min_{w} \left[ \sum_{i=1}^n (Y_i - w^\top \psi(X_i))^2 + \|w\|_{\Lambda_0}^2, \right],$$
 (3)

where  $\Lambda_0$  is a symmetric positive definite matrix, which is often chosen as  $\lambda I$  for some  $\lambda > 0$  in applications.

# Bayesian Interpretation of Ridge Regression

### Proposition 6 (Prop 15.5)

Consider probability model  $p(y|w, x) = N(w^{\top}\psi(x), \sigma^2)$ , with prior  $p_0(w) = N(0, \sigma^2 \Lambda_0^{-1})$ . Then given  $S_n = \{(X_1, Y_1), \dots, (X_n, Y_n)\}$ , we have

$$p(w|\mathcal{S}_n) = N(\hat{w}(\mathcal{S}_n), \sigma^2 \hat{\Lambda}(\mathcal{S}_n)^{-1}),$$

where  $\hat{w}(\mathcal{S}_n)$  is given by (3) and

$$\hat{\Lambda}(\mathcal{S}_n) = \sum_{i=1}^n \psi(X_i) \psi(X_i)^\top + \Lambda_0.$$

Given x, the posterior distribution of y is

$$\hat{p}(\boldsymbol{y}|\boldsymbol{x},\mathcal{S}_n) = N\left(\hat{\boldsymbol{w}}(\mathcal{S}_n)^\top \boldsymbol{\psi}(\boldsymbol{x}), \sigma^2 + \sigma^2 \boldsymbol{\psi}(\boldsymbol{x})^\top \hat{\boldsymbol{\Lambda}}(\mathcal{S}_n)^{-1} \boldsymbol{\psi}(\boldsymbol{x})\right).$$

The result holds even when the Bayesian model isn't correct.

# Proof of Proposition 6 (I/II)

It is clear that

$$p(\boldsymbol{w}|\mathcal{S}_n) \propto \exp\left(-\sum_{i=1}^n \frac{(\boldsymbol{w}^{\top}\psi(\boldsymbol{X}_i)-\boldsymbol{Y}_i)^2}{2\sigma^2}-\frac{\|\boldsymbol{w}\|_{\Lambda_0}^2}{2\sigma^2}
ight).$$

Note that (3) implies that

$$\sum_{i=1}^{n} \frac{(w^{\top}\psi(X_i) - Y_i)^2}{2\sigma^2} + \frac{\|w\|_{\Lambda_0}^2}{2\sigma^2}$$
$$= \sum_{i=1}^{n} \frac{(\hat{w}^{\top}\psi(X_i) - Y_i)^2}{2\sigma^2} + \frac{\|\hat{w}\|_{\Lambda_0}^2}{2\sigma^2} + \frac{1}{2\sigma^2}(w - \hat{w})^{\top}\hat{\Lambda}(\mathcal{S}_n)(w - \hat{w}). \quad (4)$$

# Proof of Proposition 6 (II/II)

This implies the first desired result. Moreover, given *x*, and let the random variable  $u = w^{\top} \psi(x)$  with  $w \sim p(w|S_n)$ , we have

$$u|x, \mathcal{S}_n \sim N(\hat{w}^{\top}\psi(x), \sigma^2\psi(x)^{\top}\hat{\Lambda}(\mathcal{S}_n)^{-1}\psi(x))$$

Since in posterior distribution, the observation  $y|u \sim u + \epsilon$  with  $\epsilon \sim N(0, \sigma^2)$ , we know that

$$y|x, \mathcal{S}_n \sim N(\hat{w}^{\top}\psi(x), \sigma^2\psi(x)^{\top}\hat{\Lambda}^{-1}\psi(x) + \sigma^2).$$

This implies the desired result.

# **Predictive Loss Bound**

### Theorem 7 (Thm 15.6)

Consider the ridge regression method of (3). We have the following result for any  $\sigma \ge 0$  and for all observed sequence  $S_T$ :

$$\sum_{t=1}^{T} \left[ \frac{(Y_t - \hat{w}(\mathcal{S}_{t-1})^\top \psi(X_t))^2}{b_t} + \sigma^2 \ln b_t \right]$$
$$= \inf_{w} \left[ \sum_{t=1}^{T} (Y_t - w^\top \psi(X_t))^2 + \|w\|_{\Lambda_0}^2 \right] + \sigma^2 \ln \left| \Lambda_0^{-1} \Lambda_T \right|,$$

where

$$\Lambda_t = \Lambda_0 + \sum_{s=1}^t \psi(X_s) \psi(X_s)^\top,$$

and  $b_t = 1 + \psi(X_t)^{\top} \Lambda_{t-1}^{-1} \psi(X_t)$ .

# Proof of Theorem 7 (I/II)

Assume  $w \in \mathbb{R}^d$ . We note that from Gaussian integration that

$$\begin{split} & \mathbb{E}_{w \sim p_0} \prod_{i=1}^{T} p(Y_i | w, X_i) \\ &= \int \frac{|\Lambda_0^{-1}|^{-1/2}}{(2\pi)^{(T+d)/2} \sigma^T \sigma^d} \exp\left(-\frac{1}{2\sigma^2} \sum_{i=1}^{T} (Y_i - w^\top \psi(X_i))^2 - \frac{\|w\|_{\Lambda_0}^2}{2\sigma^2}\right) \, dw \\ &= \frac{|\Lambda_0^{-1} \Lambda_T|^{-1/2}}{(2\pi)^{T/2} \sigma^T} \exp\left(-\frac{1}{2\sigma^2} \sum_{i=1}^{T} (Y_i - \hat{w}(\mathcal{S}_T)^\top \psi(X_i))^2 - \frac{\|\hat{w}(\mathcal{S}_T)\|_{\Lambda_0}^2}{2\sigma^2}\right), \end{split}$$

where the last equation used Gaussian integration with decomposition (4).

# Proof of Theorem 7 (II/II)

That is,

$$\begin{aligned} -\ln \mathbb{E}_{\boldsymbol{w}\sim p_0} \prod_{i=1}^{T} p(\boldsymbol{Y}_i | \boldsymbol{w}, \boldsymbol{X}_i) &= T \ln(\sqrt{2\pi}\sigma) + \frac{1}{2} \ln \left| \Lambda_0^{-1} \Lambda_T \right| \\ &+ \frac{1}{2\sigma^2} \sum_{i=1}^{T} (\boldsymbol{Y}_i - \hat{\boldsymbol{w}}(\boldsymbol{\mathcal{S}}_T)^\top \psi(\boldsymbol{X}_i))^2 + \frac{\|\hat{\boldsymbol{w}}(\boldsymbol{\mathcal{S}}_T)\|_{\Lambda_0}^2}{2\sigma^2}. \end{aligned}$$

Moreover, from Proposition 6, we have

$$\sum_{i=1}^{T} -\ln p(Y_t | \hat{w}(S_{t-1}), X_t)$$
  
=  $\sum_{t=1}^{T} \left[ \frac{(Y_t - \hat{w}(S_{t-1})^\top \psi(X_t))^2}{2\sigma^2 b_t} + \frac{1}{2} \ln(b_t) + \ln(\sqrt{2\pi}\sigma) \right]$ 

The desired result now follows from Theorem 4.

# Regret Bound with Bounded Response

### Corollary 8 (Cor 15.7)

Assume that  $Y_t \in [0, M]$  for  $t \ge 1$ . Consider the ridge regression method of (3), and let

$$\hat{Y}_t = \max(0, \min(M, \hat{w}(\mathcal{S}_{t-1})^\top \psi(X_t))).$$

We have

$$\sum_{t=1}^{T} (Y_t - \hat{Y}_t)^2 \leq \inf_{w} \left[ \sum_{t=1}^{T} (Y_t - w^\top \psi(X_t))^2 + \|w\|_{\Lambda_0}^2 \right] + M^2 \ln \left| \Lambda_0^{-1} \Lambda_T \right|,$$

where

$$\Lambda_T = \Lambda_0 + \sum_{s=1}^T \psi(X_s) \psi(X_s)^\top.$$

### Proof of Corollary 8

We can apply Theorem 7 by taking  $\sigma^2 = M^2$ . By using the following inequality

(

$$0 \leq rac{1-b_t}{b_t} + \ln b_t,$$

we obtain

$$\sum_{t=1}^{T} (Y_t - \hat{Y}_t)^2 \leq \sum_{t=1}^{T} \left[ (Y_t - \hat{Y}_t)^2 + M^2 \frac{1 - b_t}{b_t} + M^2 \ln b_t \right]$$
$$\leq \sum_{t=1}^{T} \left[ (Y_t - \hat{Y}_t)^2 + (Y_t - \hat{Y}_t)^2 \frac{1 - b_t}{b_t} + M^2 \ln b_t \right] \quad (5)$$
$$\leq \sum_{t=1}^{T} \left[ \frac{(Y_t - \hat{W}(\mathcal{S}_{t-1})^\top \psi(X_t))^2}{b_t} + M^2 \ln b_t \right],$$

where  $b_t$  is defined in Theorem 7. Note that (5) used  $1 - b_t \le 0$  and  $(Y_t - \hat{Y}_t)^2 \le M^2$ . The desired result is now a direct application of Theorem 7.

# Estimation of Determinant

### Proposition 9 (Simplification of Prop 15.8)

Given any  $\mathcal{X}$  and  $\psi : \mathcal{X} \to \mathcal{H}$ , where  $\mathcal{H}$  is an inner product space. Then for each  $\lambda > 0$  and integer T, the embedding entropy of  $\psi(\cdot)$  can be defined as

entro
$$(\lambda, \psi(\mathcal{X})) = \sup_{\mathcal{D}} \ln \left| I + \frac{1}{\lambda} \mathbb{E}_{X \sim \mathcal{D}} \psi(X) \psi(X)^{\top} \right|$$

If  $\sup_{X \in \mathcal{X}} \|\psi(X)\|_{\mathcal{H}} \leq B$  and  $\dim(\mathcal{H}) < \infty$ , then

$$\operatorname{entro}(\lambda,\psi(\mathcal{X})) \leq \operatorname{dim}(\mathcal{H}) \ln\left(1 + \frac{B^2}{\operatorname{dim}(\mathcal{H})\lambda}\right)$$

One can also deal with the situation of  $dim(\mathcal{H}) = \infty$  (see Proposition 15.8).

## **Proof of Proposition 9**

Let 
$$A = I + (\lambda)^{-1} \mathbb{E}_{X \sim D} \psi(X) \psi(X)^{\top}$$
 and  $d = \dim(\mathcal{H})$ , then  
 $\operatorname{trace}(A) \leq d + (\lambda)^{-1} \mathbb{E}_{X \sim D} \operatorname{trace}(\psi(X)\psi(X)^{\top}) \leq d + B^2/\lambda.$ 

Using the AM-GM inequality, we have

$$|\mathbf{A}| \leq [\operatorname{trace}(\mathbf{A})/\mathbf{d}]^{\mathbf{d}} \leq (1 + \mathbf{B}^2/(\mathbf{d}\lambda))^{\mathbf{d}}$$



### Example 10

Consider Corollary 8 with  $\Lambda_0 = \lambda I$ . We can use Proposition 9 to obtain

$$\sum_{t=1}^{T} (Y_t - \hat{Y}_t)^2$$

$$\leq \inf_{W} \left[ \sum_{t=1}^{T} (Y_t - W^{\top} \psi(X_t))^2 + \lambda \|W\|_2^2 \right] + M^2 d \ln \left(1 + \frac{TB^2}{d\lambda}\right),$$

where we assume that  $\|\psi(x)\|_2 \leq B$ , and *d* is the dimension of  $\psi(x)$ .

### Online to Batch Conversion

Assume  $(X_t, Y_t) \sim D$  are iid examples. By taking expectation with respect to D, and by using Jensen's inequality for the concave log-determinant function, we obtain (see Corollary 15.11) that with  $\Lambda_0 = \lambda I$ , we have

$$\mathbb{E}_{\mathcal{S}_{T}} \frac{1}{T} \sum_{t=1}^{T} \mathbb{E}_{X \sim \mathcal{D}} \left( f_{*}(X) - \hat{f}(\hat{w}(\mathcal{S}_{t-1}), X) \right)^{2}$$

$$\leq \inf_{W} \mathbb{E}_{X \sim \mathcal{D}} \left[ \left( f_{*}(X) - w^{\top} \psi(X) \right)^{2} + \lambda \|w\|_{2}^{2} \right]$$

$$+ \frac{M^{2} + \sigma^{2}}{T} \ln \left| I + \frac{T}{\lambda} \mathbb{E}_{X \sim \mathcal{D}} \psi(X) \psi(X)^{\top} \right|.$$

Note that this bound is superior to the Rademacher complexity bound, and the best convergence rate can be achieved is  $O(\ln T/T)$ .

# **Exponential Model Aggregation**

Consider a general loss function with Z = (X, Y):

$$\phi(\boldsymbol{w},\boldsymbol{Z})=L(f(\boldsymbol{w},\boldsymbol{X}),\boldsymbol{Y}),$$

where L(f, y) is convex with respect to f. Consider a prior  $p_0(w)$  on  $\Omega$ , and the following form of Gibbs distribution (which we will also refer to as posterior):

$$p(w|S_n) \propto \exp\left[-\eta \sum_{i=1}^n \phi(w, Z_i)\right] p_0(w),$$
 (6)

where  $\eta > 0$  is a learning rate parameter. The exponential model aggregation algorithm computes

$$\hat{f}(x|\mathcal{S}_n) = \int_{\Omega} f(w, x) p(w|\mathcal{S}_n) \, dw, \tag{7}$$

where  $p(w|S_n)$  is given by (6).

# **Online Exponential Model Aggregation**

Algorithm 1: Online Exponential Model Aggregation

**Input:**  $\eta > 0$ , { $f(w, x) : w \in \Omega$ }, prior  $p_0(w)$ **Output:**  $\hat{f}(\cdot|S_T)$ 

for 
$$t = 1, 2, ..., T$$
 do

2 Observe 
$$X_t$$

Let 
$$\hat{f}_t = \hat{f}(X_t | \mathcal{S}_{t-1})$$
 according to (7)

4 Observe 
$$Y_t$$

5 Compute 
$$L(\hat{f}_t, Y_t)$$

**Return:**  $\hat{f}(\cdot|\mathcal{S}_T)$ 

In order to analyze Algorithm 1, we need to employ the concept of  $\alpha$ -exponential concavity introduced below.

### Definition 11 (Def 15.12)

A convex function g(u) is  $\alpha$ -exponential concave for some  $\alpha > 0$  if

 $e^{-\alpha g(u)}$ 

is concave in u.

## **Properties**

### Proposition 12 (Prop 15.13)

### A convex function $\phi(u)$ is $\alpha$ exponentially concave if

$$\alpha \nabla \phi(\boldsymbol{u}) \nabla \phi(\boldsymbol{u})^{\top} \leq \nabla^2 \phi(\boldsymbol{u}).$$

### Proof.

We have

$$abla^2 oldsymbol{e}^{-lpha \phi(oldsymbol{u})} = oldsymbol{e}^{-lpha \phi(oldsymbol{u})} \left[ -lpha 
abla^2 \phi(oldsymbol{u}) + lpha^2 
abla \phi(oldsymbol{u}) 
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ight] \leq \mathbf{0}.$$

This implies the concavity of  $\exp(-\alpha\phi(u))$ .

## Examples

### Example 13

We note that if  $\phi(u)$  is both Lipschitz  $\|\nabla \phi(u)\|_2 \leq G$ , and  $\lambda$ -strongly convex, then

$$(\lambda/G^2)\nabla\phi(u)\nabla\phi(u)^{\top} \leq \lambda I \leq \nabla^2\phi(u).$$

Proposition 12 implies that  $\phi(u)$  is  $\lambda/G^2$  exponentially concave.

# Examples (cont)

### Example 14

Consider the loss function  $L(u, y) = (u - y)^2$ . If  $|u - y| \le M$ , then L(u, y) is  $\alpha$ -exponentially concave in u with  $\alpha \le 1/(2M^2)$ .

### Example 15

Consider a function  $f(\cdot)$ , and let  $L(f(\cdot), y) = -\ln f(y)$ , then  $L(f(\cdot), y)$  is  $\alpha$  exponentially concave in  $f(\cdot)$  for  $\alpha \le 1$ . This loss function is applicable to conditional probability estimate  $\ln f(y|x)$ .

# **Regret Bound**

#### Theorem 16 (Thm 15.19)

Assume that L(f, y) is  $\eta$ -exponentially concave. Then (7) satisfies the following regret bound:

$$\sum_{t=1}^T L(\hat{f}(X_t|\mathcal{S}_{t-1}), Y_t) \leq \inf_q \left[ \mathbb{E}_{w \sim q} \sum_{t=1}^T L(f(w, X_t), Y_t) + \frac{1}{\eta} \mathbb{E}_{w \sim q} \ln \frac{q(w)}{p_0(w)} \right].$$

We note that Theorem 4 is a special case of Theorem 16, with  $\eta = 1$ ,

$$L(f(w, x), y) = -\ln P(y|w, x)$$

and f(w, x) = P(y|w, x). In this case,  $\exp(-L(f, y)) = f_y$  is concave in f.

### Proof of Theorem 16

Since  $e^{-\eta L(f,y)}$  is concave in *f*, we obtain from Jensen's inequality

$$\ln \int e^{-\eta L(f(w,x),y)} p(w|\mathcal{S}_{t-1}) dw \leq \ln e^{-\eta L(\hat{f}(x|\mathcal{S}_{t-1}),y)}$$

With  $(x, y) = (X_t, Y_t)$ , this can be equivalently rewritten as

$$L(\hat{f}(X_{t}|\mathcal{S}_{t-1}), Y_{t}) \leq \frac{-1}{\eta} \ln \frac{\int_{\Omega} \exp(-\eta \sum_{i=1}^{t} L(f(w, X_{i}), Y_{i})) p_{0}(w) dw}{\int_{\Omega} \exp(-\eta \sum_{i=1}^{t-1} L(f(w, X_{i}), Y_{i})) p_{0}(w) dw}$$

By summing over t = 1 to t = T, we obtain

$$\sum_{t=1}^{T} L(\hat{f}(X_t|\mathcal{S}_{t-1}), Y_t) \leq \frac{-1}{\eta} \ln \int_{\Omega} \exp\left(-\eta \sum_{i=1}^{T} L(f(w, X_i), Y_i)\right) p_0(w) dw$$

Using Proposition 3, we obtain the desired result.

# Example: Log-Loss

### Example 17

Theorem 4 is a special case of Theorem 16, with  $\eta = 1$ ,

$$L(f(\cdot|w,x),y) = -\ln P(y|w,x)$$

and  $f(\cdot|w, x) = P(\cdot|w, x)$ . In this case,

$$\exp(-L(f(\cdot|\cdot), y)) = f(y|\cdot)$$

is a component of  $f(\cdot|\cdot)$  indexed by *y*, and thus concave in  $f(\cdot|\cdot)$ .

## Example: Least Squares

### Example 18

Assume that  $L(f, y) = (f - y)^2$ , and  $\sup |f(w, x) - y| \le M$ . Then for  $\eta \le 1/(2M^2)$ , L(f, y) is  $\eta$  exponentially concave. Therefore we have

$$\sum_{t=1}^{T} (\hat{f}(X_t | \mathcal{S}_{t-1}) - Y_t)^2 \leq \inf_{q} \left[ \mathbb{E}_{w \sim q} \sum_{t=1}^{T} (f(w, X_t) - Y_t)^2 + \frac{1}{\eta} \mathbb{E}_{w \sim q} \ln \frac{q(w)}{p_0(w)} \right]$$

In particular, if  $\Omega$  is countable, then

$$\sum_{t=1}^{T} (\hat{f}(X_t | \mathcal{S}_{t-1}) - Y_t)^2 \leq \inf_{w \in \Omega} \left[ \sum_{t=1}^{T} (f(w, X_t) - Y_t)^2 + \frac{1}{\eta} \ln \frac{1}{p_0(w)} \right]$$

Model aggregation is superior to ERM for misspecified models, because the regret with respect to the best function in the function class is still O(1/n).

# Adaptive Gradient

Algorithm 2: Adaptive SubGradient Method (AdaGrad)

**Input:**  $\eta > 0$ ,  $w_0$ ,  $A_0$ , and a sequence of loss functions  $\ell_t(w)$ **Output:**  $w_T$ 

- 1 for t = 1, 2, ..., T do
- 2 Observe loss  $\ell_t(w_{t-1})$
- 3 Let  $g_t = \nabla \ell_t(w_{t-1})$
- 4 Let  $A_t = A_{t-1} + g_t g_t^{\top}$

5 Let 
$$G_t = \operatorname{diag}(A_t)^{1/2}$$

$$\mathsf{Let} \ \widetilde{w}_t = w_{t-1} - \eta G_t^{-1} g_t$$

$$\mathbf{w} \models \mathsf{Let} \ \mathbf{w}_t = {\sf arg\,min}_{\mathbf{w}\in\Omega} (\mathbf{w} - \widetilde{\mathbf{w}}_t)^{ op} \mathbf{G}_t (\mathbf{w} - \widetilde{\mathbf{w}}_t)$$

Return: w<sub>T</sub>

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# **Regret Bound**

### Theorem 19 (Simplification with p = 0.5, Thm 15.25)

Assume that for all *t*, the loss function  $\ell_t : \Omega \to \mathbb{R}$  is convex. Then AdaGrad method has the following regret bound:

$$\sum_{t=1}^{T} \ell_t(w_{t-1}) \leq \inf_{w \in \Omega} \sum_{t=1}^{T} \ell_t(w) + \eta \operatorname{trace}(\operatorname{diag}(A_T)^{1/2}) \\ + \frac{\Delta_{\infty}^2}{2\eta} \operatorname{trace}(\operatorname{diag}(A_T)^{1/2}),$$

where  $\Delta_{\infty} = \sup\{\|w' - w\|_{\infty} : w, w' \in \Omega\}$  is the  $L_{\infty}$ -diameter of  $\Omega$ .

# Matrix Trace Function

The proof uses the fact that  $h(B) = 2 \text{trace}(B^{1/2})$  is concave in *B*, which follows from the following result.

#### Theorem 20 (Thm A.18)

Let  $S_{[a,b]}^d$  be the set of  $d \times d$  symmetric matrices with eigenvalues in [a,b]. If  $f(z) : [a,b] \to \mathbb{R}$  is a convex function, then

trace(f(W))

is a convex function on  $S^d_{[a,b]}$ . This implies that for  $W, W' \in S^d_{[a,b]}$ :

 $\operatorname{trace}(f(W')) \geq \operatorname{trace}(f(W)) + \operatorname{trace}(f'(W)(W' - W)),$ 

where f'(z) is the derivative of f(z).

### Proof of Theorem 19 (I/II)

Consider  $w \in \Omega$ . The convexity of  $\ell_t$  implies that

$$-2\eta(w_{t-1}-w)^{ op}g_t \leq 2\eta[\ell_t(w)-\ell_t(w_{t-1})].$$

Let  $G_t = \text{diag}(A_t)^{1/2}$ . We obtain the following result:

$$\begin{split} & (\tilde{w}_{t} - w)^{\top} G_{t} (\tilde{w}_{t} - w) \\ = & (w_{t-1} - \eta G_{t}^{-1} g_{t} - w)^{\top} G_{t} (w_{t-1} - \eta G_{t}^{-1} g_{t} - w) \\ = & (w_{t-1} - w)^{\top} G_{t} (w_{t-1} - w) - 2\eta (w_{t-1} - w)^{\top} g_{t} + \eta^{2} g_{t}^{\top} G_{t}^{-1} g_{t} \\ \leq & (w_{t-1} - w)^{\top} G_{t} (w_{t-1} - w) + 2\eta [\ell_{t} (w) - \ell_{t} (w_{t-1})] + \eta^{2} g_{t}^{\top} G_{t}^{-1} g_{t} \\ = & (w_{t-1} - w)^{\top} G_{t-1} (w_{t-1} - w) + (w_{t-1} - w)^{\top} (G_{t} - G_{t-1}) (w_{t-1} - w) \\ & + 2\eta [\ell_{t} (w) - \ell_{t} (w_{t-1})] + \eta^{2} \text{trace} ((G_{t}^{2})^{-1/2} (G_{t}^{2} - G_{t-1}^{2})) \\ \leq & (w_{t-1} - w)^{\top} G_{t-1} (w_{t-1} - w) + (w_{t-1} - w)^{\top} (G_{t} - G_{t-1}) (w_{t-1} - w) \\ & + 2\eta [\ell_{t} (w) - \ell_{t} (w_{t-1})] + 2\eta^{2} [\text{trace} (G_{t}) - \text{trace} (G_{t-1})]. \end{split}$$

## Proof of Theorem 19 (II/II)

We can use the fact that  $(w_t - w)^\top G_t(w_t - w) \leq (\tilde{w}_t - w)^\top G_t(\tilde{w}_t - w)$ , and then sum over t = 1 to t = T. This implies that

$$\sum_{t=1}^{T} \ell_t(w_{t-1}) \leq \sum_{t=1}^{T} \ell_t(w) + \frac{R_T}{2\eta} + \eta \left[ \operatorname{trace}(G_T) - \operatorname{trace}(G_0) \right],$$

where

$$\begin{split} R_{T} = &(w_{0} - w)^{\top} G_{0}(w_{0} - w) + \sum_{t=1}^{T} (w_{t-1} - w)^{\top} (G_{t} - G_{t-1})(w_{t-1} - w) \\ \leq & \Delta_{\infty}^{2} \operatorname{trace}(G_{0}) + \sum_{t=1}^{T} \Delta_{\infty}^{2} \operatorname{trace}(|G_{t} - G_{t-1}|) \\ \leq & \Delta_{\infty}^{2} \operatorname{trace}(G_{T}). \end{split}$$

In the first inequality, we note that  $G_t - G_{t-1}$  is a diagonal matrix.

# Interpretation of Theorem 19

AdaGrad is more effective than SGD when the gradient is sufficiently sparse, which means that trace $(\operatorname{diag}(A_T)^{1/2})$  can be similar to trace $(\operatorname{diag}(A_T))^{1/2}$ . In this case, Theorem 19 implies

trace(diag(
$$A_T$$
)<sup>1/2</sup>) =  $O(\sqrt{T})$ .

Let  $\eta = O(\Delta_{\infty})$ , then the regret bound becomes

$$O(\Delta_{\infty}\sqrt{T}).$$

Since in general

$$\Delta_{\infty} \ll \Delta_{2} \equiv \sup\{\|\boldsymbol{w}' - \boldsymbol{w}\|_{2} : \boldsymbol{w}, \boldsymbol{w}' \in \Omega\},\$$

and in the extreme case,  $\Delta_2$  can be as large as  $\Omega(\sqrt{d}\Delta_{\infty})$ , where *d* is the dimension of the model parameter. In such case, AdaGrad can be better than SGD by a factor of  $\sqrt{d}$ .

# Summary (Chapter 15)

- Bayesian Posterior Averaging (aggregation)
- Ridge Regression (second order optimization)
- Tow approaches are closely related
- Generalization
- Aggregation Methods
- AdaGrad